

## ABSTRACT OF THE DISCLOSURE

A steering control device (200) is provided with a end-of-movement reaction force generation unit (an end reaction force control portion (20)). An end reaction force generating current  $i_2$  which act as return a handle toward a straight-ahead position is rapidly generated in the vicinity of an upper and a lower limit of a vehicle wheel steering range. For example, a reaction force motor (4) may be additionally commanded using a newly generated command current  $i_2$ . Accordingly, an output torque of the reaction force motor (4) becomes proportional to a new command value  $i_n$  of an Equation  $i_n = i_1 + i_2$ , where  $i_1$  is a current command of a reaction force control portion (5). As a result of configuring the end-of-movement reaction force generation unit in this manner, for example, it is possible to generate a virtual contact resistance force (a steering reaction force) for a steering angle  $\theta$  without causing heat build-up, or the like, of a motor, when no physical limit (an end-of-movement of contact point) is provided for a rotation range of a steering wheel (handle).